



- Pin Definition:
- 1. Cathode 2. Anode
- 3. Reference



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# **General Description**

TS1431 series integrated circuits are three-terminal programmable shunt regulator diodes. These monolithic IC voltage references operate as a low temperature coefficient zener which is programmable from Vref to 36 volts with two external resistors. These devices exhibit a wide operating current range of 1.0 to 100mA with a typical dynamic impedance of  $0.22\Omega$ . The characteristics of these references make them excellent replacements for zener diodes in many applications such as digital voltmeters, power supplies, and op amp circuitry. The 2.5V reference makes it convenient to obtain a stable reference from 5.0V logic supplies, and since The TS1431 series operates as a shunt regulator, it can be used as either a positive or negative stage reference.

# Features

- Precision Reference Voltage
  - TS1431 2.495V±2%
  - TS1431A 2.495V±1%
  - TS1431B 2.495V±0.5%
- Equivalent Full Range Temp. Coefficient: 50ppm/ °C
- Programmable Output Voltage up to 36V
- Fast Turn-On Response
- Sink Current Capability of 1~100mA
- Low Dynamic Output Impedance: 0.2Ω
- Low Output Noise

# **Application**

- Voltage Monitor
- Delay Timmer
- Constant Current Source/Sink
- High-Current Shunt Regulator
- Crow Bar
- Over-Voltage / Under-Voltage Protection

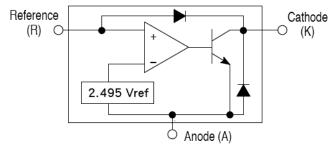
# Ordering Information

Part No.	Package	Packing
TS1431 <u>x</u> CT B0	TO-92	1Kpcs / Bulk
TS1431 <u>x</u> CT A3	TO-92	2Kpcs / Ammo
TS1431 <u>x</u> CX RF	SOT-23	3Kpcs / 7" Reel
TS1431 <u>x</u> CT B0G	TO-92	1Kpcs / Bulk
TS1431 <u>x</u> CT A3G	TO-92	2Kpcs / Ammo
TS1431 <u>x</u> CX RFG	SOT-23	3Kpcs / 7" Reel

Note: "G" denote for Green Product

Where <u>xx</u> denotes voltage tolerance Blank: ±2%, A: ±1%, B: ±0.5%

### Block Diagram



### Absolute Maximum Rating (Ta = 25°C unless otherwise noted)

Parameter		Symbol	Limit	Unit
Cathode Voltage		Vka	36	V
Continuous Cathode Current Range		lk	1 ~ +100	mA
Reference Input Current Range		Iref	-0.05 ~ +10	mA
Power Dissipation	TO-92 SOT-23	Pd	0.625 0.30	w
Junction Temperature		Tj	+150	°C
Operating Temperature Range		Toper	0 ~ +70	°C
Storage Temperature Range		Tstg	-65 ~ +150	°C



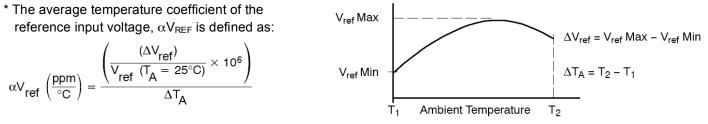
### **Recommend Operating Condition**

Parameter	Symbol	Limit	Unit
Cathode Voltage (Note 1)	V <sub>KA</sub>	Ref ~ 36	V
Continuous Cathode Current Range	Ι <sub>κ</sub>	1 ~ 100	mA

### **Recommend Operating Condition**

Parameter		Symbol	Test Conditions	Min	Тур	Мах	Unit
	TS1431		$\lambda = 10 \text{ m} \Lambda$ (Figure 1)	2.450		2.550	V
Reference voltage	TS1431A	$V_{REF}$	V <sub>KA</sub> =V <sub>REF</sub> , I <sub>K</sub> =10mA (Figure 1) Ta=25°C	2.475	2.495	2.525	
	TS1431B		Ta-25 C	2.487		2.513	
Deviation of reference input voltage		$\Delta V_{REF}$	$V_{KA} = V_{REF}$ , $I_{K} = 10mA$ (Figure 1) Ta= full range		3	17	mV
Radio of change in \	/ref to		$I_{KA}$ =10mA, $V_{KA}$ = 10V to $V_{REF}$		-1.4	-2.7	mV/V
change in cathode V	oltage	$\Delta V_{REF} / \Delta V_{KA}$	$V_{KA}$ = 36V to 10V (Figure 2)		-1.0	-2.0	
Reference Input current		I <sub>REF</sub>	R1=10KΩ, R2= ∞ , I <sub>KA</sub> =10mA Ta= full range (Figure 2)		0.7	4.0	uA
Deviation of reference input current, over temp.		$\Delta I_{REF}$	R1=10KΩ, R2= ∞ , I <sub>KA</sub> =10mA Ta= full range (Figure 2)		0.4	1.2	uA
Off-state Cathode Current		I <sub>KA</sub> (off)	$V_{REF}$ =0V (Figure 3), $V_{KA}$ =36V			1.0	uA
Dynamic Output Impedance		Z <sub>ka</sub>	f<1KHz, V <sub>KA</sub> = V <sub>REF</sub> I <sub>KA</sub> =1mA to 100mA (Figure 1)		0.22	0.5	Ω
Minimum operating cathode current		cathode $I_{KA}$ (min) $V_{KA} = V_{REF}$ (Figure 1)			0.4	0.6	mA

\* The deviation parameters  $\Delta V_{REF}$  and  $\Delta I_{REF}$  are defined as difference between the maximum value and minimum value obtained over the full operating ambient temperature range that applied.



Where: **T2-T1** = full temperature change.

 $\alpha V_{REF}$  can be positive or negative depending on whether the slope is positive or negative. Example: Maximum V<sub>REF</sub>=2.496V at 30°C, minimum V<sub>REF</sub> =2.492V at 0°C, V<sub>REF</sub> =2.495V at 25°C,  $\Delta T$ =70°C

# $\alpha V_{REF}$ | = [4mV / 2495mV] \* 10<sup>6</sup> / 70°C $\approx$ 23ppm/°C

Because minimum  $V_{\text{REF}}$  occurs at the lower temperature, the coefficient is positive.

\* The dynamic impedance ZKA is defined as:

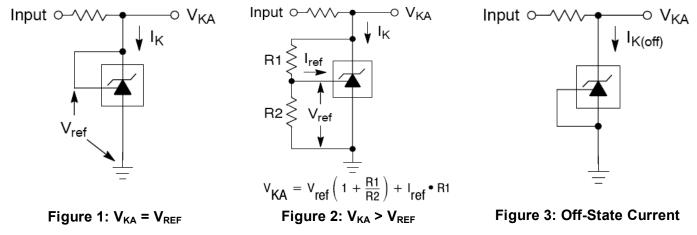
$$|Z_{KA}| = \Delta V_{KA} / \Delta I_{KA}$$

\* When the device operating with two external resistors, R1 and R2, (refer to Figure 2) the total dynamic impedance of the circuit is given by:

 $|Z_{KA}| = \Delta v / \Delta i | \approx Z_{KA} | * (1 + R1 / R2)$ 



## **Test Circuits**



### Additional Information – Stability

When The TS1431/1431A/1431B is used as a shunt regulator, there are two options for selection of  $C_L$ , are recommended for optional stability:

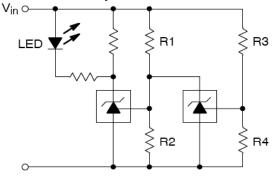
A) No load capacitance across the device, decouple at the load.

B) Large capacitance across the device, optional decoupling at the load.

The reason for this is that TS1431/1431A/1431B exhibits instability with capacitances in the range of 10nF to 1uF (approx.) at light cathode current up to 3mA (typ). The device is less stable the lower the cathode voltage has been set for. Therefore while the device will be perfectly stable operating at a cathode current of 10mA (approx.) with a 0.1uF capacitor across it, it will oscillate transiently during start up as the cathode current passes through the instability region. Select a very low capacitance, or alternatively a high capacitance (10uF) will avoid this issue altogether. Since the user will probably wish to have local decoupling at the load anyway, the most cost effective method is to use no capacitance at all directly across the device. PCB trace/via resistance and inductance prevent the local load decoupling from causing the oscillation during the transient start up phase.

Note: if the TS1431/1431A/1431B is located right at the load, so the load decoupling capacitor is directly across it, then this capacitor will have to be  $\leq 1$ nF or  $\geq 10$ uF.

### **Applications Examples**



L.E.D. indicator is 'ON' when  $V_{in}$  is between the upper and lower limits,

Lower limit =  $\left(1 + \frac{R1}{R2}\right) V_{ref}$ Upper limit =  $\left(1 + \frac{R3}{R4}\right) V_{ref}$ 



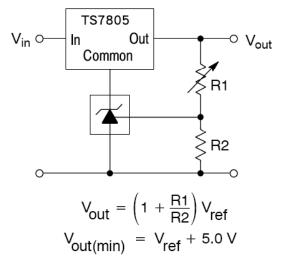
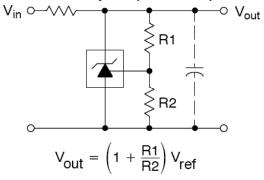


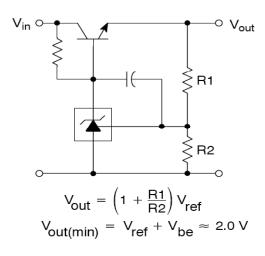
Figure 5: Output Control for Three Terminal Fixed Regulator



# **Applications Examples (Continue)**



### Figure 6: Shunt Regulator



# Figure 8: Series Pass Regulator

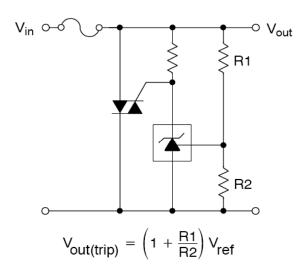
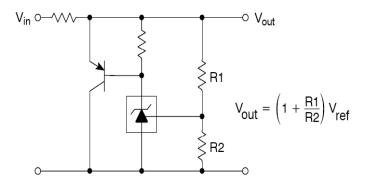
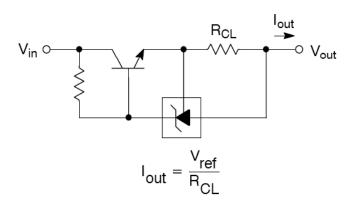


Figure 10: TRIAC Crowbar



### Figure 7: High Current Shunt Regulator



### Figure 9: Constant Current Source

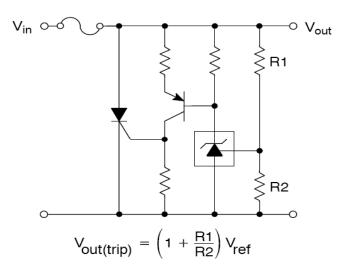
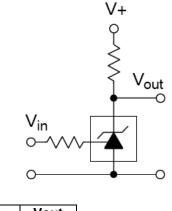


Figure 11: SCR Crowbar



# **Applications Examples (Continue)**



Vin	Vout
<vref< td=""><td>V+</td></vref<>	V+
>Vref	≈0.74V

### Figure 12: Single-Supply Comparator with Temperature-Compensated Threshold

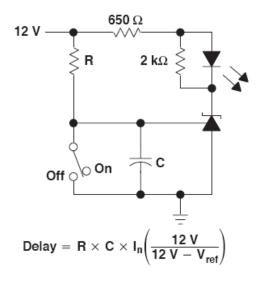


Figure 14: Delay Timer

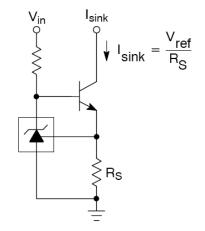
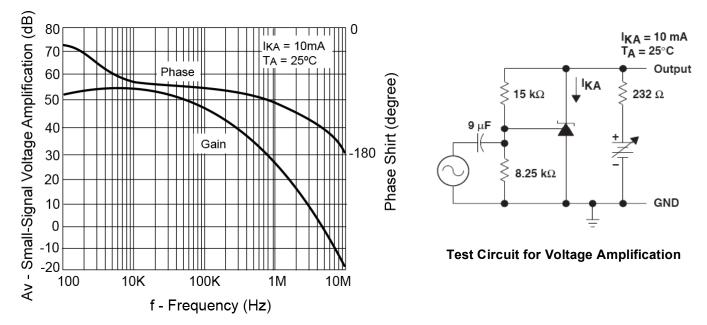


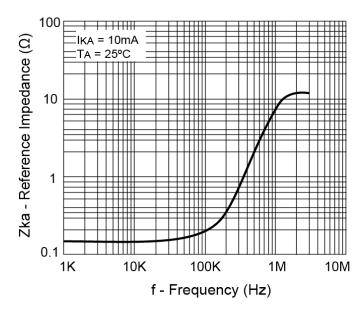
Figure 13: Constant Current Sink

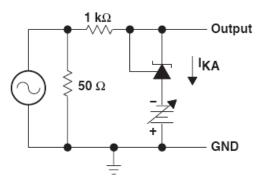


# **Typical Performance Characteristics**

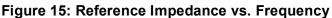








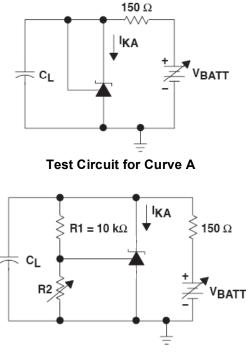
**Test Circuit for Reference Impedance** 





### 100 1 1 1 1 1 1 1 1 1 A VKA = Vref IKA - Cathode Current (mA) 90 Β νκα = 5ν C VKA = 10V 80 D VKA = 15V В 70 -TA = 25°C 60 С Stable 50 Stable А 40 30 D 20 В 10 0 0.001 0.01 0.1 1 10 CL - Load Capacitance (uF)

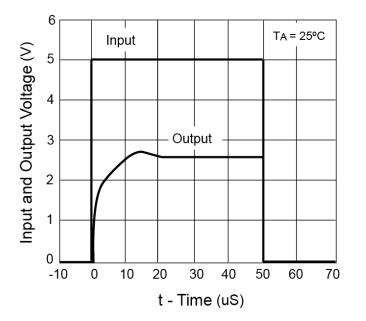
**Typical Performance Characteristics (Continue)** 

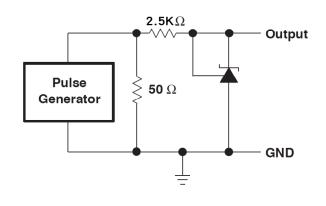


Test Circuit for Curve B, C and D

The areas under the curves represent conditions that may cause the device to oscillate. For curves B, C, and D, R2 and V+ were adjusted to establish the initial VKA and IKA conditions with CL=0. VBATT and CL then were adjusted to determine the ranges of stability.

# Figure 16: Stability Boundary Condition





Test Circuit for Pulse Response, Ik=1mA

Figure 17: Pulse Response





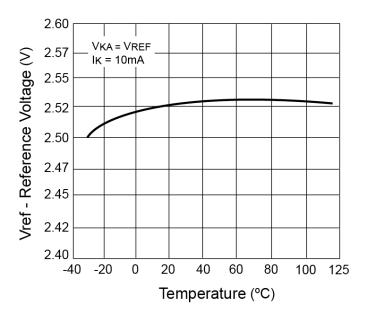


Figure 18: Reference Voltage vs. Temperature

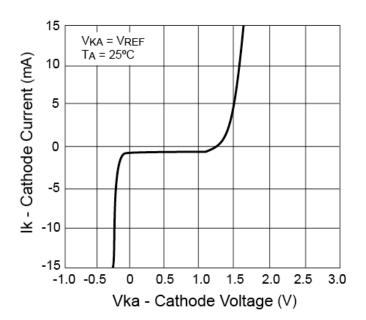


Figure 20: Cathode Current vs. Cathode Voltage

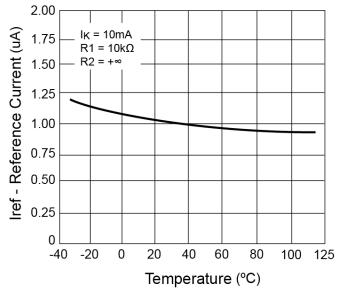


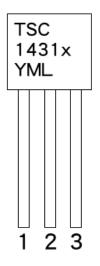
Figure 19: Reference Current vs. Temperature



# 

TO-92 DIMENSION						
DIM	MILLIMETERS		INCHES			
	MIN	MAX	MIN	MAX		
А	4.30	4.70	0.169	0.185		
В	4.30	4.70	0.169	0.185		
С	14.30(typ)		0.563(typ)			
D	0.43	0.49	0.017	0.019		
Е	2.19	2.81	0.086	0.111		
F	3.30	3.70	0.130	0.146		
G	2.42	2.66	0.095	0.105		
Н	0.37	0.43	0.015	0.017		

# **Marking Diagram**



- X = Tolerance Code
  - $(A = \pm 1\%, B = \pm 0.5\%, Blank = \pm 2\%)$

**TO-92 Mechanical Drawing** 

- Y = Year Code
- M = Month Code

(A=Jan, B=Feb, C=Mar, D=Apl, E=May, F=Jun, G=Jul, H=Aug, I=Sep, J=Oct, K=Nov, L=Dec)

L = Lot Code



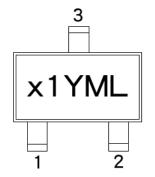
# D $\rightarrow | + G$ $\downarrow + G$



I	

SOT-23 DIMENSION						
DIM MILLIMETERS			INCHES			
DIN	MIN	MAX	MIN	MAX.		
А	0.95	BSC	0.037 BSC			
A1	1.9 I	BSC	0.074 BSC			
В	2.60	3.00	0.102	0.118		
С	1.40	1.70	0.055	0.067		
D	2.80	3.10	0.110	0.122		
E	1.00	1.30	0.039	0.051		
F	0.00	0.10	0.000	0.004		
G	0.35	0.50	0.014	0.020		
Н	0.10	0.20	0.004	0.008		
I	0.30	0.60	0.012	0.024		
J	5°	10°	5°	10°		

# Marking Diagram



- 1 = Device Code
- **X** = Tolerance Code
  - $(A = \pm 1\%, B = \pm 0.5\%, C = \pm 2\%)$
- Y = Year Code
- M = Month Code
  - (A=Jan, B=Feb, C=Mar, D=Apl, E=May, F=Jun, G=Jul, H=Aug, I=Sep, J=Oct, K=Nov, L=Dec)
- L = Lot Code



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